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Author(s): Christon, Mark A.

Bakosi, Jozsef

Francois, Marianne M. Lowrie, Robert B. Nourgaliev, Robert

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## Multiphase Flow Analysis in Hydra-TH

J. Bakosi, M. A. Christon, M. M Francois, R.B. Lowrie
Los Alamos National Laboratory

R. Nourgaliev Idaho National Laboratory

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### **ABSTRACT**



This talk presents an overview of the multiphase flow efforts with Hydra-TH. The presentation begins with a definition of the requirements and design principles for multiphase flow relevant to CASL-centric problems. A brief survey of existing codes and their solution algorithms is presented before turning the model formulation selected for Hydra-TH. The issues of hyperbolicity and well-posedness are outlined, and a three candidate solution algorithms are discussed. The development status of Hydra-TH for multiphase flow is then presented with a brief summary and discussion of future directions for this work.



## <u>OVERVIEW</u>



- Requirements & Design Principles
- Survey of Codes & Solution Algorithms
- Hydra-TH Model Formulation
- Candidate Hydra-TH Solution Algorithms
- Hydra-TH Status
- Summary & Future Directions



## HYDRA-TH: requirements & design principles

&CA5L

- Multi-(N)-fluid (user-specified) formulation
- (Discrete) mass, momentum, and energy conservation
- Ability to cover all-speeds (from nearly-incompressible to fully-compressible)
- Ability to deal with numerically stiff fluid (water) equation of state
- Robust treatment of phase appearance and disappearance
- Ability to deal with boiling/condensation (tight coupling with energy equation)
- For [1-fluid, ρ=const, operator-splitting] option, should reduce to the original HYDRA algorithm (proven to be robust/accurate/efficient)
- Solvability: hyperbolicity/well-posedness
- Efficient for large-scale unstructured-mesh HPC applications (scalable)
- Can be tightly coupled with Next-Generation System Analysis codes



## **Survey of Codes & Solution Algorithms**



- Codes Surveyed: NPHASE, NEPTUNE, CATHARE, StarCD & CCM+, Fluent, CFX, MFIX, CFDLib, TRAC, TRACE, RELAP5, RETRAN, ...
  - Documented in "Effective-Field Modeling for Multi-Fluid Flows" working notes
- Basic formulations are similar in terms of ensemble averaged conservation equations, degrees-of-freedom, and closures
  - Volume fractions, multiple velocities, multiple energy eq.'s, etc.
  - Virtually all are using a single-pressure approximation
- Approaches to hyperbolize equations
  - Bulk pressure difference, interface dynamic pressure, added mass
  - 7 equation-model of Saurel, Berry, et al. preserves hyperbolicity -- invisicid
- Solution algorithms
  - Virtually all are pressure-based
  - Many are based on SIMPLE (aka Uzawa iteration)
    - Expect slow convergence rates (ex: many 100's of iterations for small problems)
    - NPHASE combines SIMPLE-like outer iteration with coupled mass-momentum solve
  - All current work-horse T-H codes (RELAP5, TRAC, TRACE, CATHARE, RETRAN) use operator-split algorithms



#### **HYDRA-TH**: model formulation



#### (5N)-conservation equations, N-field formulation

- Mechanical & thermal non-equilibrium
- Pressure <u>equilibrium</u>
- Multiple-bulk-pressure
- <u>Hyperbolic</u> (easily provable when *N*=2 fields)
- Can implement both acoustically-filtered and fully-compressible forms
- EOS: generic; for water <u>IAPWS-IF97</u> Standard
- Multiphase closures: from NPHASE methods, Lahey, Podowski, et al.
- [ILES, LES/DES, k-ε and k-ω models in the future]
- [Interfacial area transport (IAT) in the future (from NPHASE/NEPTUNE)]

## Application Focus

#### 1. Subcooled boiling

- 2. Departure from nucleate boiling (DNB)
  - 3. Loss-of-coolant accidents (LOCA)
    - 4. Reflooding

In the future



## **HYDRA-TH**: governing equations



#### Mass:

$$\frac{\partial \alpha_k \bar{\rho}_k}{\partial t} + \nabla \cdot (\alpha_k \bar{\rho}_k \tilde{\mathbf{v}}_k) = \boxed{\Gamma_k}$$

#### Momentum:

$$\begin{split} \frac{\partial \alpha_{k} \bar{\rho}_{k} \tilde{\mathbf{v}}_{k}}{\partial t} + \nabla \cdot \left( \alpha_{k} \left[ \bar{\rho}_{k} \tilde{\mathbf{v}}_{k} \otimes \tilde{\mathbf{v}}_{k} + \boxed{\bar{p}_{k}} \right) = \left( \boxed{p_{ki}} - \boxed{\tau_{ki}} \right) \nabla \alpha_{k} + \boxed{\mathbf{M}_{k}'} + \\ + \nabla \cdot \left( \alpha_{k} \left[ \boxed{\bar{\tau}_{k}} + \boxed{\mathbf{T}_{k}^{Re}} \right] \right) + \alpha_{k} \bar{\rho}_{k} \boxed{\tilde{\mathbf{b}}_{k}} + \boxed{\mathbf{v}_{ki}^{m}} \boxed{\Gamma_{k}} \end{split}$$

#### Total energy:

$$\begin{split} \frac{\overline{\partial}}{\partial_{t}} \left( \alpha_{k} \overline{\rho}_{k} \tilde{e}_{k} \right) + \nabla \cdot \left( \alpha_{k} \left[ \overline{\rho}_{k} \tilde{e}_{k} + \overline{p}_{k} \right] \tilde{\mathbf{v}}_{k} \right) &= \mathbf{M}_{k}^{'} \cdot \tilde{\mathbf{v}}_{k} + \left( p_{ki} - \overline{\tau}_{ki} \right) \tilde{\mathbf{v}}_{k} \cdot \nabla \alpha_{k} + \\ &+ \nabla \cdot \left( \alpha_{k} \left[ \tilde{\mathbf{v}}_{k} \left( \overline{\tau}_{k} + \mathbf{T}_{k}^{Re} \right) - \overline{\mathbf{q}}_{k} - \overline{\mathbf{q}}_{k}^{Re} \right] \right) + \end{split}$$

$$+ \alpha_k \bar{\rho}_k \left( \tilde{r}_k + \tilde{\mathbf{b}}_k \cdot \tilde{\mathbf{v}}_k \right) + \Gamma_k \left( u_{ki} + \frac{\left( v_{ki}^e \right)^2}{2} \right) + E_k + W_k'$$

#### To close:

- + N equations of state,  $\bar{p}_{k}$   $(\bar{\rho}_{k}, \tilde{u}_{k})$
- + Constitutive physics (for terms in boxes \_\_\_\_)
- + Compatibility condition,  $\sum \alpha_k = 1$
- + Bulk pressure difference models,  $\Delta \bar{p}_{(ij)}\left(\mathbf{U}\right), \ i \neq j, \ (i,j) = 0,...,N-1$





### Wave/Eigen-structure

#### Mass:

$$\left[ \frac{\partial \alpha_k \bar{\rho}_k}{\partial t} + \nabla \cdot (\alpha_k \bar{\rho}_k \tilde{\mathbf{v}}_k) \right] = \left[ \Gamma_k \right]$$

#### Momentum:

$$\frac{\partial \alpha_{k} \bar{\rho}_{k} \tilde{\mathbf{v}}_{k}}{\partial t} + \nabla \cdot \left(\alpha_{k} \left[\bar{\rho}_{k} \tilde{\mathbf{v}}_{k} \otimes \tilde{\mathbf{v}}_{k} + \left[\bar{p}_{k}\right]\right) = \left[p_{ki} - \tau_{ki}\right] \nabla \alpha_{k} + \left[\mathbf{v}_{ki}\right] + \nabla \cdot \left(\alpha_{k} \left[\bar{\tau}_{k}\right] + \left[\mathbf{v}_{ki}\right] + \left[\mathbf{v}_{ki}\right] \right] \Gamma_{k} \right)$$

#### Total energy:

$$\frac{\partial}{\partial_{t}} \left( \alpha_{k} \bar{\rho}_{k} \tilde{e}_{k} \right) + \nabla \cdot \left( \alpha_{k} \left[ \bar{\rho}_{k} \tilde{e}_{k} + \bar{p}_{k} \right] \tilde{\mathbf{v}}_{k} \right) = \mathbf{v} \cdot \tilde{\mathbf{v}}_{k} + \mathbf{v} \cdot \left[ \mathbf{v}_{ki} - \tau_{ki} \right] \tilde{\mathbf{v}}_{k} \cdot \nabla \alpha_{k} + \nabla \cdot \left( \alpha_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right) + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \bar{\tau}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \mathbf{v}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}_{k} \left[ \mathbf{v}_{k} + \mathbf{v}_{k} \right] \right] + \mathbf{v} \cdot \left[ \mathbf{v}$$

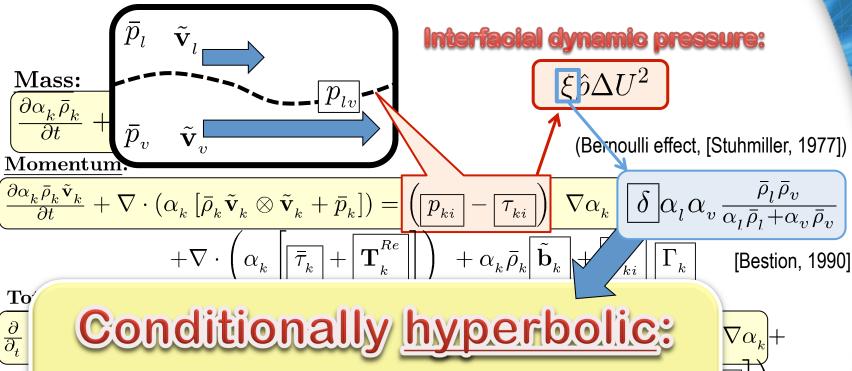
$$+ \alpha_k \bar{\rho}_k \left( \left[ \tilde{r}_k \right] + \left[ \tilde{\mathbf{b}}_k \right] \cdot \tilde{\mathbf{v}}_k \right) + \left[ \Gamma_k \right] \left( u_k \right)$$

This is a non-physical model (used in TRAC/TRACE)

Non-hyperbolic IF







## $S \setminus 1$

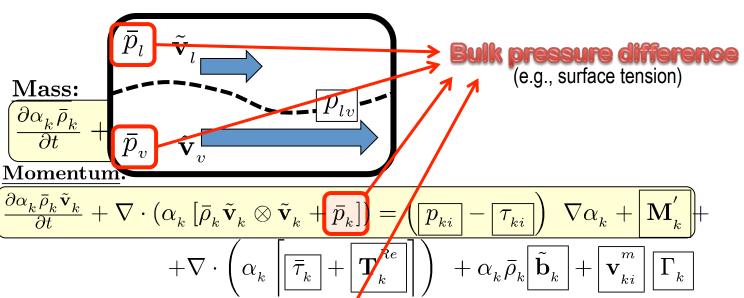
 $\delta \geq 1$ 

$$+ \alpha_k \bar{\rho}_k \left( \left[ \tilde{r}_k \right] + \left[ \tilde{\mathbf{b}}_k \right] \cdot \tilde{\mathbf{v}}_k \right) + \left[ \Gamma_k \right] \left[ u_{ki} \right]$$

CATHARE NEPTUNE/OVAP







Total energy:

$$\frac{\partial}{\partial_{t}} \left( \alpha_{k} \bar{\rho}_{k} \tilde{e}_{k} \right) + \nabla \cdot \left( \alpha_{k} \left[ \bar{\rho}_{k} \tilde{e}_{k} + \bar{p}_{k} \right] \tilde{\mathbf{v}}_{k} \right) = \mathbf{M}_{k}' \cdot \tilde{\mathbf{v}}_{k} + \left( p_{ki} - \tau_{ki} \right) \tilde{\mathbf{v}}_{k} \cdot \nabla \alpha_{k} + \nabla \cdot \left( \alpha_{k} \left[ \tilde{\mathbf{v}}_{k} \left( \bar{\tau}_{k} + \mathbf{T}_{k}^{Re} \right) - \bar{\mathbf{q}}_{k} - \bar{\mathbf{q}}_{k}^{Re} \right] \right) + \nabla \cdot \left( \alpha_{k} \left[ \tilde{\mathbf{v}}_{k} \left( \bar{\tau}_{k} + \bar{\mathbf{v}}_{k} \right) - \bar{\mathbf{q}}_{k} - \bar{\mathbf{q}}_{k}^{Re} \right] \right) + \left[ \alpha_{k} \bar{\rho}_{k} \left( \bar{r}_{k} + \bar{\mathbf{b}}_{k} \cdot \tilde{\mathbf{v}}_{k} \right) + \left[ \Gamma_{k} \left( u_{ki} + \frac{\left( v_{ki}^{e} \right)^{2}}{2} \right) + \left[ E_{k} \right] + W_{k}' \right]$$





#### Mass:

$$\left( \frac{\partial \alpha_k \bar{\rho}_k}{\partial t} + \nabla \cdot (\alpha_k \bar{\rho}_k \tilde{\mathbf{v}}_k) \right) = \left[ \Gamma_k \right]$$

#### **Added mass:**

$$\mu \bar{\rho}_c \frac{\mathrm{d}_{\mathrm{d}} \Delta \vec{U}}{\mathrm{d}t}$$

#### Momentum:

$$\left(\frac{\partial \alpha_{k} \bar{\rho}_{k} \tilde{\mathbf{v}}_{k}}{\partial t} + \nabla \cdot (\alpha_{k} \left[\bar{\rho}_{k} \tilde{\mathbf{v}}_{k} \otimes \tilde{\mathbf{v}}_{k} + \bar{p}_{k}\right]) = \left(\boxed{p_{ki}} - \boxed{\tau_{ki}}\right) \nabla \alpha_{k} + \boxed{\mathbf{M}_{k}'}\right) + \left(\frac{\partial \alpha_{k} \bar{\rho}_{k} \tilde{\mathbf{v}}_{k}}{\partial t} + \nabla \cdot (\alpha_{k} \left[\bar{\rho}_{k} \tilde{\mathbf{v}}_{k} \otimes \tilde{\mathbf{v}}_{k} + \bar{p}_{k}\right]\right) = \left(\boxed{p_{ki}} - \boxed{\tau_{ki}}\right) \nabla \alpha_{k} + \boxed{\mathbf{M}_{k}'}\right) + \left(\frac{\partial \alpha_{k} \bar{\rho}_{k} \tilde{\mathbf{v}}_{k}}{\partial t} + \nabla \cdot (\alpha_{k} \left[\bar{\rho}_{k} \tilde{\mathbf{v}}_{k} \otimes \tilde{\mathbf{v}}_{k} + \bar{p}_{k}\right]\right) = \left(\boxed{p_{ki}} - \boxed{\tau_{ki}}\right) \nabla \alpha_{k} + \boxed{\mathbf{M}_{k}'}\right) + \left(\frac{\partial \alpha_{k} \bar{\rho}_{k} \tilde{\mathbf{v}}_{k}}{\partial t} + \nabla \cdot (\alpha_{k} \left[\bar{\rho}_{k} \tilde{\mathbf{v}}_{k} \otimes \tilde{\mathbf{v}}_{k} + \bar{p}_{k}\right]\right) + \left(\boxed{p_{ki}} - \boxed{\tau_{ki}}\right) \nabla \alpha_{k} + \boxed{\mathbf{M}_{k}'}\right) + \left(\frac{\partial \alpha_{k} \bar{\rho}_{k} \tilde{\mathbf{v}}_{k}}{\partial t} + \nabla \cdot (\alpha_{k} \left[\bar{\rho}_{k} \tilde{\mathbf{v}}_{k} \otimes \tilde{\mathbf{v}}_{k} + \bar{p}_{k}\right]\right) + \left(\boxed{p_{ki}} - \boxed{\tau_{ki}}\right) \nabla \alpha_{k} + \boxed{\mathbf{M}_{k}'}\right) + \left(\boxed{p_{ki}} - \boxed{\tau_{ki}}\right) + \left(\boxed{p_{ki}} - \boxed{\tau_{ki}}\right) \nabla \alpha_{k} + \boxed{\mathbf{M}_{k}'}\right) + \left(\boxed{\mathbf{M}_{k}'}\right) + \left(\boxed{\mathbf{M}_{k}'$$

$$+\nabla\cdot\left(\alpha_{k}\left[\left[\overline{\tau}_{k}\right]+\left|\mathbf{T}_{k}^{Re}\right|\right]\right)+\alpha_{k}$$

#### Total energy:

$$\frac{\left[\frac{\partial}{\partial_{t}}\left(\boldsymbol{\alpha}_{k}\bar{\boldsymbol{\rho}}_{k}\tilde{\boldsymbol{e}}_{k}\right) + \nabla\cdot\left(\boldsymbol{\alpha}_{k}\left[\bar{\boldsymbol{\rho}}_{k}\tilde{\boldsymbol{e}}_{k} + \bar{\boldsymbol{p}}_{k}\right]\tilde{\mathbf{v}}_{k}\right) = \mathbf{M}_{k}^{'}\right]\cdot\tilde{\mathbf{v}}_{k}}{+\nabla\cdot\left(\boldsymbol{\alpha}_{k}\left[\bar{\boldsymbol{\tau}}_{k}\right] + \left[\bar{\boldsymbol{\tau}}_{k}\right]\right) + \nabla\cdot\left(\boldsymbol{\alpha}_{k}\left[\bar{\boldsymbol{\tau}}_{k}\right] + \left[\bar{\boldsymbol{\tau}}_{k}\right]\right) + \nabla\cdot\left(\boldsymbol{\alpha}_{k}\left[\bar{\boldsymbol{\tau}}_{k}\right]\right) + \nabla\cdot$$

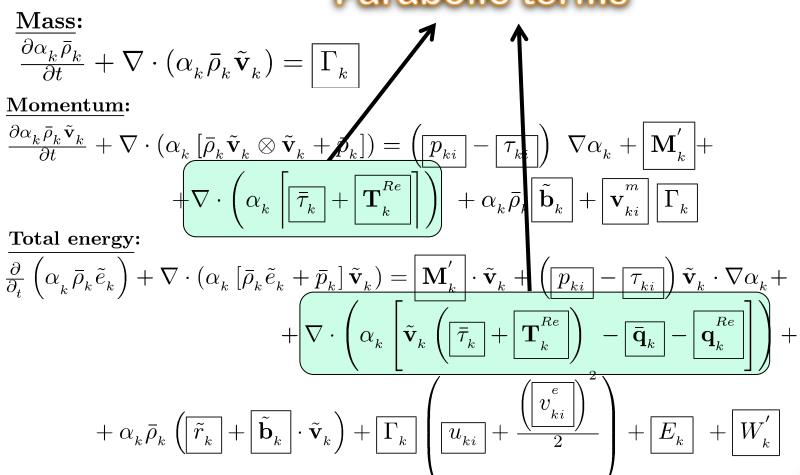
## RELAP5 NPHASE NEPTUNE

$$+ \alpha_k \bar{\rho}_k \left( \left[ \tilde{r}_k \right] + \left[ \tilde{\mathbf{b}}_k \right] \cdot \tilde{\mathbf{v}}_k \right) + \left[ \Gamma_k \right] \left( \left[ u_{ki} \right] + \frac{\left( \left[ v_{ki}^e \right] \right)}{2} \right) + \left[ E_k \right] + \left[ W_k' \right]$$





#### Parabolic terms



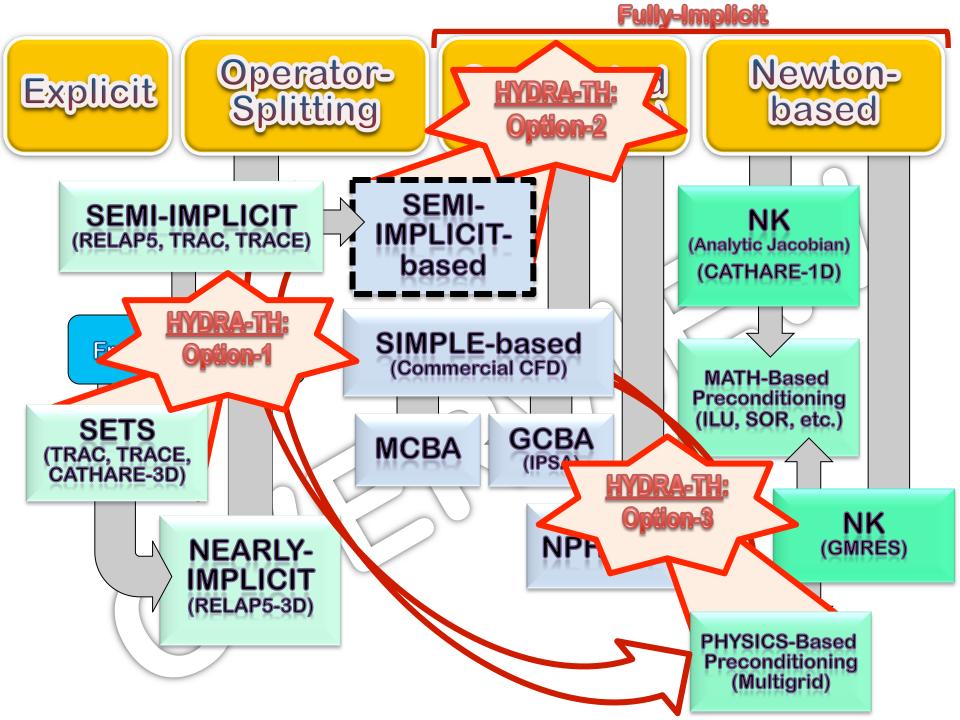




## HYDRA-TH:

# Solution algorithm (preliminary design)

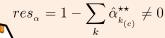




## **HYDRA-TH**: solution algorithm, optic

No compatibility enforced

SETS-based operator-splitting (Fractional



1. Volume fraction update ("mass stabilizer")

$$a_{c,c}^{(k)}\left(\mathbf{U}^{\star}\right)\hat{\alpha}_{k_{(c)}}^{\star\star} + \sum_{n}^{N} a_{c,n}^{(k)}\left(\mathbf{U}^{\star}\right)\hat{\alpha}_{k_{(n)}}^{\star\star} = b_{c}^{(k)}\left(\mathbf{V}^{\star}\right)\hat{\alpha}_{k_{(c)}}^{\star\star} = \frac{b_{c}^{(k)} + \sum\limits_{m \neq k}^{K} c_{c}^{(k,m)} \tilde{\mathbf{v}}_{m_{(c)}}^{\star} - \sum\limits_{n}^{N} a_{c,n}^{(k)} \tilde{\mathbf{v}}_{k_{(n)}}^{\star}}{\sum\limits_{k_{(n)} \in \mathbb{N}} c_{k_{(n)}}^{(k)} \left(\mathbf{V}^{\star}\right)\hat{\alpha}_{k_{(n)}}^{\star\star}} = b_{c}^{(k)}\left(\mathbf{V}^{\star}\right)\hat{\alpha}_{k_{(c)}}^{\star\star} = \frac{b_{c}^{(k)} + \sum\limits_{m \neq k}^{K} c_{c}^{(k,m)} \tilde{\mathbf{v}}_{m_{(c)}}^{\star} - \sum\limits_{n}^{N} a_{c,n}^{(k)} \tilde{\mathbf{v}}_{k_{(n)}}^{\star}}{\sum\limits_{k_{(n)} \in \mathbb{N}} c_{k_{(n)}}^{(k)} \left(\mathbf{V}^{\star}\right)\hat{\alpha}_{k_{(n)}}^{\star\star}} = b_{c}^{(k)}\left(\mathbf{V}^{\star}\right)\hat{\alpha}_{k_{(n)}}^{\star\star} = b_{c}^{(k)}\left(\mathbf{V}^{\star}\right)\hat{\alpha}_{k$$

**Phasic mass** 

$$\tilde{\mathbf{v}}_{k_{(c)}}^{\diamond} = \frac{b_{c}^{(k)} + \sum_{m \neq k}^{K} c_{c}^{(k,m)} \tilde{\mathbf{v}}_{m_{(c)}}^{\star} - \sum_{n}^{N} a_{c,n}^{(k)} \tilde{\mathbf{v}}_{k_{(n)}}^{\star}}{a_{c,c}^{(k)} + \sum_{n}^{K} c_{c}^{(k,m)}}$$

ILU or **AMG** 

2. Velocity update ("momentum stabilizer", SINCE-based)

No mass/energy conservation enforced

$$\hat{ ilde{\mathbf{v}}}_{k_{(c)}}^{\star\star} + \sum\limits_{n}^{N} a_{c,n}^{(k)} \hat{ ilde{\mathbf{v}}}_{k_{(n)}}^{\star\star} == b_{c}^{(k)} + \sum\limits_{m 
eq k}^{K} \left| c_{c}^{(k,m)} \right|$$

$$\hat{\tilde{\mathbf{v}}}_{k_{(c)}}^{\star\star} + \sum_{n}^{N} a_{c,n}^{(k)} \hat{\tilde{\mathbf{v}}}_{k_{(n)}}^{\star\star} == b_{c}^{(k)} + \sum_{m \neq k}^{K} \left[ c_{c}^{(k,m)} \frac{b_{c}^{(m)} + \sum_{j \neq m,k}^{K} c_{c}^{(m,j)} \hat{\mathbf{v}}_{j_{(c)}}^{\diamond} - \sum_{n}^{N} a_{c,n}^{(m)} \hat{\mathbf{v}}_{m_{(n)}}^{\diamond} }{a_{c,c}^{(m)} + \sum_{j \neq m}^{K} c_{c}^{(m,j)}} \right]$$

$$\hat{\mathbf{v}}_{k_{(c)}}^{\star\star} + \sum_{n=1}^{N} a_{c,n}^{(k)} \hat{\tilde{\mathbf{v}}}_{k_{(n)}}^{\star\star} = b_{c}^{(k)} + \sum_{m \neq k}^{K} \left[ c_{c}^{(k,m)} \frac{b_{c}^{(m)} + \sum_{j \neq m,k}^{K} c_{c}^{(m,j)} \hat{\mathbf{v}}_{j_{(c)}}^{\star} - \sum_{n=1}^{N} a_{c,n}^{(m)} \hat{\tilde{\mathbf{v}}}_{m_{(n)}}^{\star} \right]$$

$$\hat{\mathbf{v}}_{k_{(c)}}^{\star\star} + \sum_{n=1}^{N} a_{c,n}^{(k)} \hat{\tilde{\mathbf{v}}}_{k_{(n)}}^{\star\star} = b_{c}^{(k)} + \sum_{m \neq k}^{K} \left[ c_{c}^{(k,m)} \frac{b_{c}^{(m)} + \sum_{j \neq m,k}^{K} c_{c}^{(m,j)} \hat{\mathbf{v}}_{j_{(c)}}^{\star} - \sum_{n=1}^{N} a_{c,n}^{(m)} \hat{\tilde{\mathbf{v}}}_{m_{(n)}}^{\star\star} \right]$$

$$\hat{\mathbf{v}}_{k_{(c)}}^{\star\star} + \sum_{n=1}^{N} a_{c,n}^{(k)} \hat{\tilde{\mathbf{v}}}_{k_{(n)}}^{\star\star} = b_{c}^{(k)} + \sum_{m \neq k}^{K} \left[ c_{c}^{(k,m)} \frac{b_{c}^{(m)} + \sum_{j \neq m,k}^{K} c_{c}^{(m,j)} \hat{\tilde{\mathbf{v}}}_{j_{(c)}}^{\star} - \sum_{j \neq m}^{N} a_{c,n}^{(m)} \hat{\tilde{\mathbf{v}}}_{m_{(n)}}^{\star\star} \right]$$

$$\hat{\mathbf{v}}_{k_{(c)}}^{\star\star} + \sum_{n=1}^{N} a_{c,n}^{(k)} \hat{\tilde{\mathbf{v}}}_{k_{(n)}}^{\star\star} = b_{c}^{(k)} + \sum_{m \neq k}^{K} \left[ c_{c}^{(m,j)} \frac{b_{c}^{(m)} + \sum_{j \neq m}^{K} c_{c}^{(m,j)} \hat{\tilde{\mathbf{v}}}_{j_{(c)}}^{\star\star} - \sum_{j \neq m}^{K} c_{c}^{(m,j)} \hat{\tilde{\mathbf{v}}}_{j_{(c)}}^{\star\star} \right]$$

$$\hat{\mathbf{v}}_{k_{(c)}}^{\star\star} + \sum_{n=1}^{N} a_{c,n}^{(n)} \hat{\mathbf{v}}_{k_{(n)}}^{\star\star} + \sum_{j \neq m}^{K} c_{c}^{(m,j)} \hat{\tilde{\mathbf{v}}}_{j_{(c)}}^{\star\star} + \sum_{j \neq m}^{K} c_{c}^{(m,j)} \hat{\tilde{\mathbf{v}}}_{j$$

3. Enthalpy update ("energy stabilizer")

$$a^{(k)} \left(\mathbf{U}^{\star}\right) \hat{\tilde{h}}^{\star\star} + \sum_{c}^{N} a^{(k)} \left(\mathbf{U}^{\star}\right) \hat{\tilde{h}}^{\star\star}_{k_{(n)}} = b_{c}^{(k)} \left(\mathbf{U}^{\star}\right)$$
Compressibility

Phasic energy conservation equations

**AMG** 

(ILU or AMG)

5. <u>Turbulence Equations</u>

<u>lon</u> (mass/energy conservation + compatibility)

6. Other scalar transport equations



derivative of [Liles, Reed, 1978] "semiimplicit" (ICE-based) algorithm

### **HYDRA-TH:** solution algorithm, option-2



Fully-Implicit, Segregated (Picard-iteration)

- 1. Volume fraction update ("mass stabilizer")
- 2. Velocity update ("momentum stabilizer", SINCE-based)
- 3. Enthalpy update ("energy stabilizer")
- 4. Pressure-Helmholtz Equation
- 5. Turbulence Equations

steps algorithm

Fractional

6. Other scalar transport equations

**Converged?** 

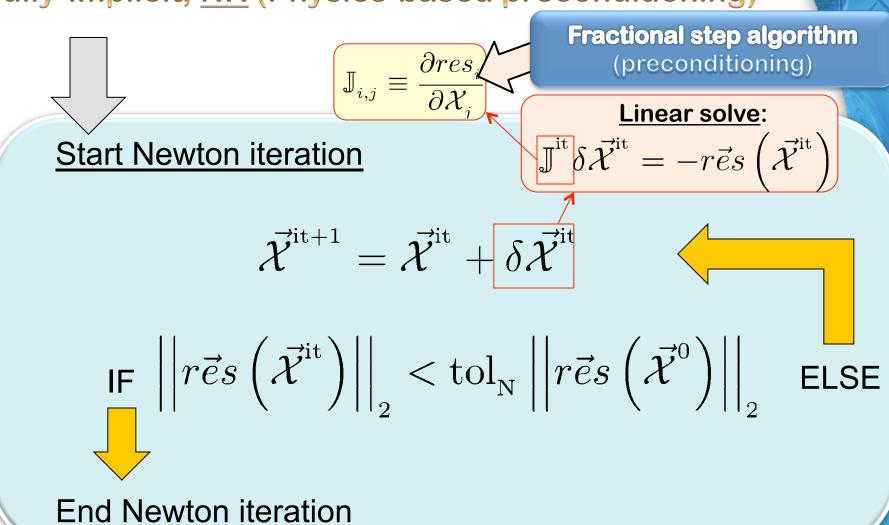


## **HYDRA-TH:** solution algorithm, option-3



**Nuclear Energy** 

#### Fully-Implicit, NK (Physics-based preconditioning)



### **HYDRA-TH:** Status

- Prototype multiphase physics is in place
  - Running simple problems and solving N-momentum equations w. single pressure
  - Volume fractions treated as passive scalars for now
  - All keywords, BC's, IC's inherited from the virtual incompressible physics

#### General development plan

• Re-use all existing BC's, IC's, materials, transport solvers, and turbulence statistics on a phasic basis

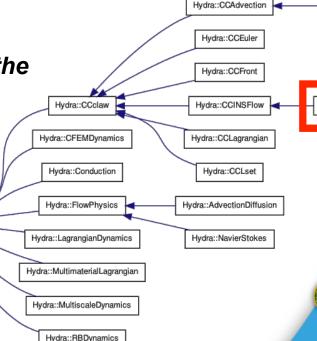
Hvdra::StrPhvsics

Hvdra::UnsPhysics

Implement both segregated and fully-coupled solution algorithms

 Segregated solvers will provide the physics-based preconditioning

 Preserve existing ALE methods for FSI





Hvdra::CCBurgers

Hydra::CCMultiPhas

## **Summary & Future Directions**



#### The basic formulation is relatively well defined at this point

- Some questions remain on multiphase closures, e.g., the form of lift forces, mass exchange terms, etc.
  - May require some additional research to adequately define source terms
- A number of questions/algorithmic decisions will be answered over the next 3-4 months

#### Prototype multiphase virtual physics is in place

- Able to solve multiple momentum equations with identical BC's and obtain correct solutions
- Volume fraction transport (i.e., continuity) is in place
- Extension for multiple energy equations appears straightforward
- Additional effort required to integrate steam tables, additional constitutive and EOS models

#### On-track for L3:THM.CFD.P5.06 milestone

 Initial two-phase laminar test case to be based on DEBORA experiments is targeted – time permitting









## NPHASE Solution Algorithm a few general notes

Consortium for Advanced Simulation of LV/Rs

- 2 approaches: segregated or coupled mass/momentum
- Coupled mass/momentum approach preferred approach
  - Better stability and robustness
- User routines for closure terms (drag force, lift interfacial force, wall interfacial force, turbulence dispersion interfacial force)
- Closure terms treated differently in segregated and coupled solver
  - Segregated algorithm: linearized drag force, other terms, other terms added as RHS terms held constant during iterations.
  - Coupled algorithm: linearized terms added to LHS and full model term added to RHS



## NPHASE Solution Algorithm (Coupled Solver) Coupled Mass/Momentum – Segregated Enthalpy

- Solve for velocity, pressure, volume fractions
  - Variables: (total variables is 5\*Nfield)
    - Velocity (3), pressure (1) and volume fraction (1) per field
    - Density held constant → volume fraction equation
  - Equations:
    - Mass (continuity) (1 per field)
    - u, v, w momentum (3 per field)
    - Constraint sum of volume fractions = 1 (1 total)
    - Jump equations p<sub>k</sub>-p=0 (P equilibrium) (Nfield-1)
- Solve enthalpy, turbulence k-e, species concentration
- Update density as function of T
- Iterate until convergence



# NEPTUNE (NURETH10 paper) Pressured-based method with mass/momentum/ energy coupling

- predict velocities through partially linearized momentum equations (other variables are frozen and taken at previous time step)
- Mass/momentum/energy coupling
  - Momentum equation using predicted velocity (frozen convective/ diffusive parts and pressure and volume fractions treated implicitly)
  - Coupled with mass and total enthalpy equation
  - Iterative solver for pressure, volume fraction, total enthalpy, velocity, density (function of p and h). Enthalpy, thermodynamic properties, volume fractions prediction, pressure equation correction, update velocities, iterate until convergence (convergence is sum volume fractions=1)
- Update other variables (turbulence, interfacial areas)



#### **NEPTUNE CFD V1.0**

#### Interfacial momentum transfer terms

$$\vec{M}_{ki} = \vec{M}_{k}^{D} + \vec{M}_{k}^{MA} + \vec{M}_{k}^{L} + \vec{M}_{k}^{DT}$$

Drag force

$$\vec{M}_{g}^{D} = -\vec{M}_{l}^{D} = -\frac{1}{8} a_{i} \rho_{1} C_{D} | \vec{u}_{g} - \vec{u}_{l} | (\vec{u}_{g} - \vec{u}_{l})$$

Added mass (virtual mass)

$$\vec{M}_{g}^{MA} = -\vec{M}_{l}^{MA} = -C_{MA}\alpha \frac{1+2\alpha}{1-\alpha} \rho_{l} \left[ \left( \frac{\partial \vec{u}_{g}}{\partial t} + \vec{u}_{g} \cdot \nabla \vec{u}_{g} \right) - \left( \frac{\partial \vec{u}_{l}}{\partial t} + \vec{u}_{l} \cdot \nabla \vec{u}_{l} \right) \right]$$

Lift force

$$\vec{M}_g^L = -\vec{M}_l^L = -C_L \alpha \rho_l (\vec{u}_g - \vec{u}_l) \times (\nabla \times \vec{u}_l)$$

 $C_{MA}=0.5$ 

Turbulent dispersion

$$C_L = 1$$

$$\vec{M}_{g}^{DT} = -\vec{M}_{l}^{DT} = -C_{DT}\rho_{l}K_{l}\nabla\alpha$$

$$C_{DT} = 1$$
 (DEDALE)

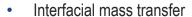
$$C_{DT} = 2.5$$
 (DEBORA)

Guelfi A. et al., NEPTUNE: A New Software Platform for Advanced Nuclear Thermal Hydraulics, Nuclear Science and Engineering, 156, 281-324, 2007



## **NEPTUNE CFD V1.0**

#### Interfacial heat and mass transfer terms



$$\Gamma_{g} = -\Gamma_{l} = \frac{-q_{li} - q_{gi} + q_{e}}{H_{g} - H_{l}}$$

 $q_{li} = h_{li}(T_{sat} - T_l)$   $h_{li} = \frac{\lambda_l}{d_s} \text{Nu}$ 

Liquid to interface heat transfer

$$Ja \le 0$$

$$Nu = 2 + 0.6 Re^{0.5} Pr^{0.33}$$

Interface to vapor heat transfer

$$Ja \ge 0$$

$$Ja \ge 0 \qquad Nu = Max(Nu_1, Nu_2, Nu_3)$$

$$Nu_1 = \sqrt{\frac{4Pe}{\pi}}$$
  $Nu_2 = \frac{12}{\pi}Ja$ 

$$Nu_2 = \frac{12}{\pi} Ja$$

$$Nu_3 = 2$$

$$q_{gi} = \frac{\alpha \rho_g C_{pg}}{\delta t} \left( T_{sat} - T_g \right)$$



$$Ja = \frac{\rho_l C_{pl} (T_l - T_{sat})}{\rho g L}$$

$$Pe = \frac{d_s U_r}{a_l}$$

$$Re = \frac{d_s U_r}{V_I}$$

$$\Pr = \frac{\mathbf{v}_l}{a_l}$$



## NEPTUNE CFD V1.0 wall heat transfer terms



Wall heat transfer

$$q_w = q_c + q_q + q_e$$

"single phase" like heat transfer through contact area A<sub>c</sub> between the liquid and the duct wall

with heat transfer coefficient

$$q_c = A_c h_{\log} (T_w - T_l)$$

Quenching effect

$$h_{\log} = \rho_l C_{pl} \frac{u^*}{T^+}$$

Phase change heat flux (bubbles nucleated on the wall surface)

$$q_q = A_q t_q f \frac{2\lambda_l (T_w - T_l)}{\sqrt{\pi a_l t_q}}$$

$$q_e = f \frac{\pi}{6} d_{nuc}^3 \rho_g LN$$

 $u^*$  wall friction velocity

T<sup>+</sup> non-dimensional temperature in the wall boundary layer



## NEPTUNE CFD V1.0 interfacial area equation



$$\frac{\partial a_i}{\partial t} + \nabla \cdot (a_i \vec{u}_i) = \frac{2}{3} \frac{a_i}{\alpha \rho_g} \left( \Gamma_{g,i} - \alpha \frac{d\rho_g}{dt} \right) + \pi d_{nuc}^2 \Phi_n^{NUC} + \Phi_{a_i}^{CO} + \Phi_{a_i}^{BK}$$

mass transfer and nucleation coalescence breakup density change effect

Assume spherical bubbles

$$d_s = \frac{6\alpha}{a_i} \qquad n = \frac{\alpha}{\pi d_s^3 / 6} = \frac{1}{36\pi} \frac{a_i^3}{\alpha^2}$$

Sauter mean diameter

Bubble number density



### **Mass Conservation Algorithm**



- 1) estimate velocities solve momentum equations implicitly using p<sup>n</sup> (predictor step)
- $\rightarrow$  2) Find pressure correction  $\delta p_i$ 
  - 3) Update pressure, density, velocity

$$\rho^{k+1} \simeq \rho^k + \left(\frac{\partial \rho_j}{\partial \rho}\right)^k \delta \rho_i + \left(\frac{\partial \rho_j}{\partial T}\right)^k \delta T_i \qquad \text{If weakly compressible}$$

- 4) Solve continuity equation for volume fractions
  - Enforce sum of volume fractions to unity, by ((1-a), renormalization or underrelaxation
- 5) iterate until convergence



## Volume Conservation Algorithm (IPSA)



- 1) first estimate of volume fractions by solving implicitly continuity equation using u<sup>n</sup>
- 2) first estimate of velocity by solving implicitly momentum equation
- →• 3) Find pressure correction using  $(\alpha_1^k + \delta \alpha_1) + (\alpha_2^k + \delta \alpha_2) = 1$  to form equation for  $\delta p$ 
  - 4) Update pressure, volume fraction, velocity
  - 5) iterate until convergence
  - 6) if energy equation, solve for T, update density

$$\rho^{k+1} \simeq \rho^k + \left(\frac{\partial \rho_j}{\partial \rho}\right)^k \delta \rho_i + \left(\frac{\partial \rho_j}{\partial \tau}\right)^k \delta \tau_i \quad \text{If weakly compressible}$$

